My Little Toolbox for Code Ensemble Performance Analysis

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A Very Quick Historical Overview

- Shannon ('48): random coding as a simple tool for proving \exists good codes.
- Elias ('55,'56); Fano ('61); Gallager ('65, '68): exponential error bounds.
- Shannon, Gallager, Berlekamp ('67): lower bounds: SP, SLB.
- Csiszár & Körner ('81): the method of types.
- Many: extensions, improvements; ensembles of structured codes.

Random coding – a paradigm on its own right.

Traditional Bounding Techniques

- $P_{e}(\mathsf{ML decoder}) \leq P_{e}(\text{another (easier) decoder}).$
- Jensen's inequality: $\mathbf{E}Z^{\rho} \leq (\mathbf{E}Z)^{\rho}$, $0 \leq \rho \leq 1$ (Gallager–style bounds).
- Simple union bound.
- Union bound with truncation: $P[\cup_j A_j] \leq \min\{1, \sum_j P[A_j]\}.$
- Union bound with a power parameter: $P[\cup_j A_j] \leq (\sum_j P[A_j])^{\rho}$, $0 \leq \rho \leq 1$.
- Union bound with intersection: $P[\cup_j A_j] \leq \sum_j P[A_j \cap G] + P[G^{C}]$.
- "Power distribution" inequality: $(\sum_i a_i)^s \leq \sum_i a_i^s$, $0 \leq s \leq 1$ (Forney '68).

All these tools facilitate the analysis a great deal but at the risk of compromising exponential tightness.

Main message of this talk: It is often possible to preserve exponential tightness by bypassing some of the above inequalities.

My Little Toolbox

- Type class enumeration (on top of the MoT).
- Analogue of the MoT for infinite alphabets.

Difficulty: Summations of Exponentially Many Terms

Many derivations are associated with summations of exponentially many terms, e.g.,

$$\overline{P_{\mathsf{e}}} \leq \sum_{\boldsymbol{y}} \mathbf{E} \left\{ P(\boldsymbol{y}|\boldsymbol{X})^{1/(1+\rho)} \right\} \cdot \mathbf{E} \left[\sum_{m} P(\boldsymbol{y}|\boldsymbol{X}_{m})^{1/(1+\rho)} \right]^{\rho},$$

$$\overline{P_{\mathsf{C}}} = \frac{1}{M} \mathbf{E} \left\{ \sum_{\boldsymbol{y}} \max_{m} P(\boldsymbol{y} | \boldsymbol{X}_{m}) \right\} = \frac{1}{M} \lim_{\beta \to \infty} \sum_{\boldsymbol{y}} \mathbf{E} \left\{ \left[\sum_{m} P(\boldsymbol{y} | \boldsymbol{X}_{m})^{\beta} \right]^{1/\beta} \right\}$$

In some situations (e.g., the BC, the IFC, the GPC, the wiretap channel, erasure/list decoding), the optimal likelihood function = sum of exponentially many terms,

Broadcast channel:
$$score_i = \sum_m P(y|x_{m,i})$$

Interference channel: $score_i = \sum P(y|x_i, x_m)$

m

A Natural Remedy: Type Class Enumerators

The idea:

$$\sum_{\boldsymbol{m}} P(\boldsymbol{y}|\boldsymbol{X}_{\boldsymbol{m}})^{\beta} = \sum_{\boldsymbol{Q}} N\boldsymbol{y}(\boldsymbol{Q}) \cdot P(\boldsymbol{y}|\boldsymbol{x}_{\boldsymbol{Q}})^{\beta} = \sum_{\boldsymbol{Q}} N\boldsymbol{y}(\boldsymbol{Q}) \cdot e^{n\beta f(\boldsymbol{Q})},$$

where

Ny(Q) = number of X_m in a given type Q of x given y.

What have we gained?

- **D** f exponentially many terms $\rightarrow \sum$ of polynomially few terms.
- ▶ $Ny(Q) \sim \text{Binomial}(e^{nR}, e^{-nI(Q)}) \text{easy to handle.}$
- Marginals of $\{Ny(Q)\}$ almost always suffice; Pairs are ~ independent.

Consequence: Avoiding the Use of Jensen's Inequality

$$\mathbf{E}\left\{\left[\sum_{m} P(\boldsymbol{y}|\boldsymbol{X}_{m})^{\beta}\right]^{1/\beta}\right\} = \mathbf{E}\left[\sum_{Q} N\boldsymbol{y}(Q) \cdot e^{n\beta f(Q)}\right]^{1/\beta}$$
$$\stackrel{:}{=} \mathbf{E}\left[\max_{Q} N\boldsymbol{y}(Q) \cdot e^{n\beta f(Q)}\right]^{1/\beta}$$
$$= \mathbf{E}\left\{\max_{Q} [N\boldsymbol{y}(Q)]^{1/\beta} \cdot e^{nf(Q)}\right\}$$
$$\stackrel{:}{=} \mathbf{E}\left\{\sum_{Q} [N\boldsymbol{y}(Q)]^{1/\beta} \cdot e^{nf(Q)}\right\}$$
$$= \sum_{Q} \mathbf{E}\left\{[N\boldsymbol{y}(Q)]^{1/\beta}\right\} \cdot e^{nf(Q)}.$$

- We just have to know how to assess moments of Ny(Q).
- Equivalently, deal with the large deviations behavior.

Properties of $N \sim \text{Binomial}(e^{nA}, e^{-nB})$

Drastic difference between A > B and A < B: phase transition at A = B. Moments:

$$E\{N^s\} \stackrel{\cdot}{=} \begin{cases} \exp\{ns(A-B)\} & A > B\\ \exp\{n(A-B)\} & A < B \end{cases}$$

Intuition:

■ A > B: double-exponential concentration of N around its mean $e^{n(A-B)}$.

•
$$A < B: E\{N^s\} = \sum_{n \ge 1} n^s P[N=n] \doteq 1^s P[N=1] \doteq e^{n(A-B)}$$

Properties of $N \sim \text{Binomial}(e^{nA}, e^{-nB})$ (Cont'd)

Large deviations behavior:

$$\mathsf{Pr}\{N \ge e^{\lambda n}\} \stackrel{.}{=} e^{-nE},$$

with

$$E = \begin{cases} [B - A]_+ & [A - B]_+ \ge \lambda\\ \infty & \text{elsewhere} \end{cases}$$

Intuition – "interesting" for A < B and $\lambda \leq 0$: $P[N \geq 1] \doteq e^{-n(B-A)}$.

$$\Pr\{N \le e^{\lambda n}\} \stackrel{.}{=} \begin{cases} 1 & A \le B + [\lambda]_+\\ 0 & \text{elsewhere} \end{cases}$$

Example – Exponentially Tight Evaluation of $\overline{P_{c}}$

Consider the BSC with crossover probability p. Using the relation

$$\mathbf{E}\{N\boldsymbol{y}(Q)^{1/\beta}\} \stackrel{.}{=} \begin{cases} \exp\{n[R - I_Q(X;Y)]/\beta\} & R > I_Q(X;Y) \\ \exp\{n[R - I_Q(X;Y)]\} & R < I_Q(X;Y) \end{cases}$$

plugging it to the expression of $\overline{P_{C}}$, and using the MoT, we get

$$\overline{P_{\mathsf{C}}} \stackrel{:}{=} \exp\{-nD(\delta_{\mathsf{GV}}(R)\|p)\}$$
$$= \exp\left\{-n\left[\delta_{\mathsf{GV}}(R)\ln\frac{1}{p} + (1 - \delta_{\mathsf{GV}}(R))\ln\frac{1}{1 - p} - h_2(\delta_{\mathsf{GV}}(R)\right]\right\}$$

where $\delta_{GV}(R)$ is the (smaller) solution to the equation

$$\ln 2 - h_2(\delta) = R.$$

Example (Cont'd)

It is interesting to compare it to the result of using Jensen's inequality:

$$\overline{P_{\mathbf{C}}} = \frac{1}{M} \lim_{\beta \to \infty} \sum_{\mathbf{y}} \mathbf{E} \left\{ \left[\sum_{m} P(\mathbf{y} | \mathbf{X}_{m})^{\beta} \right]^{1/\beta} \right\}$$
$$\leq \frac{1}{M} \lim_{\beta \to \infty} \sum_{\mathbf{y}} \left[\mathbf{E} \sum_{m} P(\mathbf{y} | \mathbf{X}_{m})^{\beta} \right]^{1/\beta}$$
$$\doteq \exp \left(-n \left[\min \left\{ \ln \frac{1}{p}, \ln \frac{1}{1-p} \right\} - h_{2}(\delta_{\mathsf{GV}}(R)] \right] \right)$$

Reminder: the red expression should be compared to

$$\delta_{\mathsf{GV}}(R) \ln \frac{1}{p} + (1 - \delta_{\mathsf{GV}}(R)) \ln \frac{1}{1 - p}$$

of the exponentially tight evaluation of the previous slide.

Application to Random Binning

Consider the process of random binning:

Each $x \in \mathcal{X}^n$ is randomly assigned to a bin $z = f(x) \sim \text{Unif}\{1, \dots, e^{nR}\}$. At the decoder

$$\hat{\boldsymbol{x}}(\boldsymbol{y}, z) = \arg \max_{\boldsymbol{x} \in f^{-1}(z)} P(\boldsymbol{x}|\boldsymbol{y})$$

Then,

$$\begin{array}{ll} \overline{P_{\mathsf{e}}} &=& \mathsf{Pr} \bigcup_{\boldsymbol{x}' \neq \boldsymbol{x}} \{f(\boldsymbol{x}') = f(\boldsymbol{x}), \ P(\boldsymbol{x}'|\boldsymbol{y}) \geq P(\boldsymbol{x}|\boldsymbol{y}) \} \\ & \stackrel{\cdot}{=} & \sum_{\boldsymbol{x}\boldsymbol{y}} P(\boldsymbol{x},\boldsymbol{y}) \sum_{Q_{X'Y} \in \mathcal{E}} \mathsf{Pr} \{N(Q_{X'Y},f(\boldsymbol{x})) \geq 1\} \end{array}$$

where \mathcal{E} is the class of all $\{Q_{X'Y}\}$ with $\mathbf{E}_{Q'} \ln P(X|Y) \ge \mathbf{E}_Q \ln P(X|Y)$ and where the type class enumerator

$$N(Q_{X'Y}, z) = |\mathcal{T}(Q_{X'Y}|\boldsymbol{y}) \cap f^{-1}(z)| \sim \mathsf{Binomial}(|\mathcal{T}(Q_{X'Y}|\boldsymbol{y})|, e^{-nR}).$$

Avoid Bounding Indicator Functions by Chernoff Bounds

Consider the error+erasure event a la Forney ('68): Instead of

$$\Pr\{\mathcal{E}_1\} = \Pr\left\{\frac{P(\boldsymbol{y}|\boldsymbol{x}_m)}{\sum_{m' \neq m} P(\boldsymbol{y}|\boldsymbol{X}_{m'})} < e^{nT}\right\} \le e^{nsT} \mathbf{E}\left\{\left(\sum_{m' \neq m} \frac{P(\boldsymbol{y}|\boldsymbol{X}_{m'})}{P(\boldsymbol{y}|\boldsymbol{x}_m)}\right)^{s}\right\}$$
$$\text{use} : \Pr\{\mathcal{E}_1\} = \Pr\left\{\sum_{m' \neq m} P(\boldsymbol{y}|\boldsymbol{X}_{m'}) > e^{-nT}P(\boldsymbol{y}|\boldsymbol{x}_m)\right\}$$
$$= \Pr\left\{\sum_{Q} N\boldsymbol{y}(Q)e^{nf(Q)} > e^{-nT}e^{nf(Q_m)}\right\}$$
$$\stackrel{:}{=} \Pr\left\{\max_{Q} N\boldsymbol{y}(Q)e^{nf(Q)} > e^{-nT}e^{nf(Q_m)}\right\}$$
$$\stackrel{:}{=} \Pr\left\{\bigcup_{Q} \left\{N\boldsymbol{y}(Q)e^{nf(Q)} > e^{n[f(Q_m) - T]}\right\}$$
$$\stackrel{:}{=} \max_{Q} \Pr\left\{N\boldsymbol{y}(Q) > e^{n[f(Q_m) - f(Q) - T]}\right\}$$

and now the large deviations properties of a single Ny(Q) are invoked...

What if Those Sums Appear Also in the Denominator?

Consider the likelihood decoder that randomly selects \hat{m} under the posterior:

$$\overline{P_{\mathbf{e}|m=0}} = \mathbf{E} \left\{ \frac{\sum_{m=1}^{M-1} P(\mathbf{Y}|\mathbf{X}_m)}{\sum_{m=0}^{M-1} P(\mathbf{Y}|\mathbf{X}_m)} \right\}$$

$$\mathbf{E} \left\{ \frac{\sum_{m=1}^{M-1} P(\boldsymbol{y}|\boldsymbol{X}_{m})}{P(\boldsymbol{y}|\boldsymbol{x}_{0}) + \sum_{m=1}^{M-1} P(\boldsymbol{y}|\boldsymbol{X}_{m})} \right\}$$

$$= \int_{0}^{1} \mathsf{d}\boldsymbol{s} \cdot \mathsf{Pr} \left\{ \frac{\sum_{m=1}^{M-1} P(\boldsymbol{y}|\boldsymbol{X}_{m})}{P(\boldsymbol{y}|\boldsymbol{x}_{0}) + \sum_{m=1}^{M-1} P(\boldsymbol{y}|\boldsymbol{X}_{m})} \ge \boldsymbol{s} \right\}$$

$$= n \cdot \int_{0}^{\infty} \mathsf{d}\boldsymbol{\theta} e^{-n\boldsymbol{\theta}} \mathsf{Pr} \left\{ \frac{\sum_{m=1}^{M-1} P(\boldsymbol{y}|\boldsymbol{X}_{m})}{P(\boldsymbol{y}|\boldsymbol{x}_{0}) + \sum_{m=1}^{M-1} P(\boldsymbol{y}|\boldsymbol{X}_{m})} \ge e^{-n\boldsymbol{\theta}} \right\}$$

$$\doteq \int_{0}^{\infty} \mathsf{d}\boldsymbol{\theta} e^{-n\boldsymbol{\theta}} \mathsf{Pr} \left\{ \sum_{m=1}^{M-1} P(\boldsymbol{y}|\boldsymbol{X}_{m}) \ge e^{-n\boldsymbol{\theta}} P(\boldsymbol{y}|\boldsymbol{x}_{0}) \right\}$$

and the rest is as before.

What if ... in the Denominator? (Cont'd)

Sometimes random denominators can be handled using transform methods. For example, let $X_i \sim \mathcal{N}(0, \sigma^2)$, i = 1, ..., n, be independent. Then,

$$\mathbf{E}\left\{\frac{1}{\sum_{i=1}^{n} X_i^2}\right\} = ???$$

What if ... in the Denominator? (Cont'd)

Sometimes random denominators can be handled using transform methods. For example, let $X_i \sim \mathcal{N}(0, \sigma^2)$, i = 1, ..., n, be independent. Then,

$$\mathbf{E}\left\{\frac{1}{\sum_{i=1}^{n}X_{i}^{2}}\right\} = \mathbf{E}\left\{\int_{0}^{\infty}dt \cdot \exp\left[-t\sum_{i=1}^{n}X_{i}^{2}\right]\right\}$$
$$= \int_{0}^{\infty}dt \cdot \mathbf{E}\left\{\exp\left[-t\sum_{i=1}^{n}X_{i}^{2}\right]\right\}$$
$$= \int_{0}^{\infty}\frac{dt}{(1+2\sigma^{2}t)^{n/2}}$$
$$= \left\{\begin{array}{cc}\infty & n \leq 2\\\frac{1}{(n-2)\sigma^{2}} & n > 2\end{array}\right.$$

In the memoryless finite–alphabet (FA) case, we usually think of the type class of a given x as the set of all x'

- \checkmark with the same empirical distribution as x,
- \checkmark that are permutations of x.

These definitions are specific to the FA memoryless case.

An alternative definition that lends itself to extensions:

 $\mathcal{T}(\boldsymbol{x}) = \left\{ \boldsymbol{x}': P(\boldsymbol{x}') = P(\boldsymbol{x}) \text{ for every memoryless source } P \right\}.$

For a general parametric family of sources $\{P_{\theta}, \theta \in \Theta\}$:

$$\mathcal{T}(\boldsymbol{x}) = \left\{ \boldsymbol{x}': \ P_{\theta}(\boldsymbol{x}') = P_{\theta}(\boldsymbol{x}) \text{ for every } \theta \in \Theta \right\}.$$

If $\{P_{\theta}, \theta \in \Theta\}$ is an exponential family:

$$P_{\theta}(\boldsymbol{x}) = \frac{\exp\left\{-\sum_{i=1}^{k} \theta_{i} \phi_{i}(\boldsymbol{x})\right\}}{Z(\theta)},$$

then

$$\mathcal{T}(\boldsymbol{x}) = \{ \boldsymbol{x}' : \phi_i(\boldsymbol{x}') = \phi_i(\boldsymbol{x}), \ i = 1, 2, ..., k \}.$$

FA memoryless:
$$\phi_i(\boldsymbol{x}) = \sum_{t=1}^n \mathcal{I}\{x_t = i\}$$

FA Markov:
$$\phi_{ij}(x) = \sum_{t=1}^{n} \mathcal{I}\{x_t = i, x_{t+1} = j\}$$

Gaussian memoryless:
$$\phi_1(\boldsymbol{x}) = \sum_{t=1}^n x_t; \ \phi_2(\boldsymbol{x}) = \sum_{t=1}^n x_t^2.$$

Zero-mean, Gaussian AR(p): $\phi_i(\mathbf{x}) = \sum_{t=1}^n x_t x_{t+i}, i = 0, 1, \dots, k$

The main building blocks (just like in the ordinary MoT):

- A computable expression for |T(x)|, or Vol{T(x)}.
- Make sure that number of different types is not too large.
- If $\mathcal{X} = \mathbb{I}\mathbb{R}$ (say, the Gaussian case), we have two problems:
 - $Vol{T(x)} = 0.$
 - **J** The space is unbounded \rightarrow infinitely many types.

First problem – allow some tolerance ϵ :

$$\mathcal{T}_{\epsilon}(\boldsymbol{x}) = \left\{ \boldsymbol{x}': |\phi_i(\boldsymbol{x}') - \phi_i(\boldsymbol{x})| \leq \epsilon, \ i = 1, 2, \dots, k \right\}.$$

But this still does not resolve the second problem.

Second problem – confine attention to a bounded region in \mathbb{R}^n (say, a sphere), outside of which the probability decays with a large enough exponent.

To assess the exponent of Vol{ $\mathcal{T}(x)$ }:

$$1 \ge \int_{\mathcal{T}_{\epsilon}(\boldsymbol{x})} d\boldsymbol{x}' \cdot P_{\theta}(\boldsymbol{x}') \stackrel{\cdot}{=} \mathsf{Vol}\{\mathcal{T}_{\epsilon}(\boldsymbol{x})\} \cdot P_{\theta}(\boldsymbol{x}),$$

leading to
$$\operatorname{Vol}\{\mathcal{T}_{\epsilon}(\boldsymbol{x})\} \stackrel{\cdot}{\leq} \frac{1}{P_{\theta}(\boldsymbol{x})} = \exp\left\{\ln Z(\theta) + \sum_{i=1}^{k} \theta_{i} \phi_{i}(\boldsymbol{x})\right\}$$

and since this is
$$\forall \theta$$
: $\mathsf{Vol}\{\mathcal{T}_{\epsilon}(\boldsymbol{x})\} \leq \min_{\theta} \exp\left\{\ln Z(\theta) + \sum_{i=1}^{k} \theta_{i} \phi_{i}(\boldsymbol{x})\right\}.$

Exponentially tight as the minimizer θ^* assigns $P_{\theta^*}{\mathcal{T}_{\epsilon}(x)} \approx 1$ (WLLN). The same idea applies to assess volumes to conditional types:

$$\mathcal{T}_{\epsilon}(\boldsymbol{x}|\boldsymbol{y}) = \left\{ \boldsymbol{x}': |\phi_i(\boldsymbol{x}',\boldsymbol{y}) - \phi_i(\boldsymbol{x},\boldsymbol{y})| \leq \epsilon, \ i = 1, 2, \dots, k \right\}.$$

Here one defines an exponential family of channels.

A challenge (relevant to ISI channels) is to assess the volume of a conditional type defined by both $\frac{1}{n} \sum_{t} g(x_t, y_t)$ and $\sum_{t=1}^{n} h(x_t, x_{t+j})$, j = 1, ..., k, for some g and h. For example, the volume of

$$\mathcal{T}(\phi, \psi, \mu | \boldsymbol{y}) = \left\{ \boldsymbol{x} : \sum_{t=1}^{n} f(x_t) = n\phi, \sum_{t=1}^{n} h(x_t, x_{t-1}) = n\psi, \sum_{t=1}^{n} g(x_t, y_t) = n\mu \right\}$$

is
$$\int_{\mathbb{R}^n} \mathsf{d}x \delta\left(\sum_{t=1}^n f(x_t) - n\phi\right) \delta\left(\sum_{t=1}^n h(x_t, x_{t+1}) - n\psi\right) \delta\left(\sum_{t=1}^n g(x_t, y_t) - n\mu\right).$$

Next, represent
$$\delta(A) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \exp\{i\omega A\} d\omega$$

then interchange the integrations, and finally, use the saddle–point method. Such a derivation is doable at least when f, g and h are all quadratic (the Gaussian case), as this is a Gaussian integral (Huleihel, Salamatian, Merhav & Médard, 2017).

Some Results ...

Example 1: List Decoding (IT, Nov. 2014)

- ▶ A code $C = \{x_0, x_1, ..., x_{M-1}\}$, $M = e^{nR}$, is selected at random.
- The marginal of each codeword $x_i \in \mathcal{X}^n$ is $\text{Unif}\{\mathcal{T}(Q)\}$.
- The channel $P(\boldsymbol{y}|\boldsymbol{x})$ is a DMC.
- I The index I of the transmitted message x_I is Unif $\{0, 1, \ldots, M-1\}$.
- The decoder outputs the indices of the L most likely messages.
- Error event: I is not on the list.
- Regimes: fixed list size (FLS) and exponential list size (ELS).

Example 1: List Decoding (Cont'd)

A general, non-asymptotic bound:

Theorem: The average probability of list error, $\overline{P_e}$, associated with the optimal list decoder, is upper bounded by

$$\overline{P_e} \leq \sum_{\boldsymbol{x}.\boldsymbol{y}} P(\boldsymbol{x}) P(\boldsymbol{y}|\boldsymbol{x}) \exp\left\{-n\boldsymbol{L} \left[\hat{I}\boldsymbol{x}\boldsymbol{y}(X;Y) + \frac{\ln\boldsymbol{L}}{n} - R - O\left(\frac{\log n}{n}\right)\right]_+\right\},\$$

where P(x) is the uniform distribution over $\mathcal{T}(Q)$ and $\hat{I}_{xy}(X;Y)$ is the empirical mutual information induced by (x, y).

The proof is by a large deviations analysis of the binomial RV

$$N(\boldsymbol{x}, \boldsymbol{y}) = \sum_{m=1}^{M-1} \mathcal{I}\{P(\boldsymbol{y}|\boldsymbol{X}_m) \ge P(\boldsymbol{y}|\boldsymbol{x})\}.$$

Example 1: List Decoding (Cont'd)

The dependence on *L* appears twice:

$$\overline{P_{\mathsf{e}}} \leq \sum_{\boldsymbol{x}, \boldsymbol{y}} P(\boldsymbol{x}) P(\boldsymbol{y} | \boldsymbol{x}) \exp \left\{ -\underbrace{n\boldsymbol{L}}_{\mathsf{FLS}} \left[\hat{I}_{\boldsymbol{x}\boldsymbol{y}}(X; Y) + \frac{\overbrace{\ln\boldsymbol{L}}}{n} - R - O\left(\frac{\log n}{n}\right) \right]_{+} \right\},\$$

In the FLS regime, $\frac{\ln L}{n} \to 0$, and averaging $\exp\{-nL[\hat{I}_{xy}(X;Y) - R]_+\}$ yields

 $\overline{P_e} \stackrel{\cdot}{\leq} e^{-nE(R,L,Q)}, \quad \text{where}$

$$E(R,L,Q) \stackrel{\triangle}{=} \min_{\tilde{P}_{Y|X}} \{ D(\tilde{P}_{Y|X} \| P_{Y|X} | Q) + L \cdot [\tilde{I}(X;Y) - R]_+ \},$$

The best exponent is obtained by maximizing over Q to yield

$$E(R,Q) = \max_{Q} E(R,L,Q).$$

Example 1: List Decoding (Cont'd)

$$\overline{P_{\mathsf{e}}} \leq \sum_{\boldsymbol{x},\boldsymbol{y}} P(\boldsymbol{x}) P(\boldsymbol{y}|\boldsymbol{x}) \exp\left\{-nL\left[\hat{I}_{\boldsymbol{x}\boldsymbol{y}}(X;Y) + \frac{\ln L}{n} - R - O\left(\frac{\log n}{n}\right)\right]_{+}\right\},\$$

In the ELS regime, $\frac{\ln L}{n} = \lambda$. By defining

$$\mathcal{E} = \left\{ (\boldsymbol{x}, \boldsymbol{y}) : \hat{I}_{\boldsymbol{x}} \boldsymbol{y}(X; Y) + \lambda - R \ge \epsilon \right\}.$$

we see that the conribution of \mathcal{E} is $\leq \exp(-n\epsilon e^{\lambda n}) \stackrel{.}{=} e^{-n\infty}$, and so,

$$\overline{P_e} \stackrel{\cdot}{\leq} \Pr\{\mathcal{E}^c\} \stackrel{\cdot}{=} \exp\left\{-n \min_{\{\tilde{P}_{Y|X}: \ \tilde{I}(X;Y) \leq R-\lambda\}} D(\tilde{P}_{Y|X} \| P_{Y|X} | Q)\right\}$$
$$\stackrel{\triangle}{=} \exp\{-n E_{\mathsf{sp}}(R-\lambda, Q)\}$$

which, for the optimum Q, becomes $\exp\{-nE_{sp}(R - \lambda)\}$ — meeting the converse bound of Shannon–Gallager–Berlekamp ('67).

Example 2: Erasure/List S–W Decoding (2014)

Let $(\mathbf{X}, \mathbf{Y}) \sim \prod_{i=1}^{n} P(x_i, y_i)$.

- x source to be encoded.
- y side info @ decoder.

Encoder: $f : \mathcal{X}^n \to \{0, 1, ..., M - 1\}, M = e^{nR}$.

 $z = f(\boldsymbol{x}).$

Random binning: For every $x \in \mathcal{X}^n$, z is selected independently at random from $\{0, 1, \dots, M-1\}$.

Example 2: Erasure/List S–W Decoding (Cont'd)

Erasure/list decoder: Given $y \in \mathcal{Y}^n$ and z, calculate for all $\hat{x} \in f^{-1}(z)$:

$$\frac{P(\hat{\boldsymbol{x}}, \boldsymbol{y})}{\sum_{\boldsymbol{x}' \in f^{-1}(z) \setminus \{\hat{\boldsymbol{x}}\}} P(\boldsymbol{x}', \boldsymbol{y})}.$$

If $\geq e^{nT}$, \hat{x} is a candidate.

- If there are no candidates an erasure is declared.
- If there is exactly one candidate ordinary decoding: \hat{x} =candidate.
- If there is more than one candidate a list is of all candidates is created.

Define \mathcal{E}_1 as the event where the real x is not a candidate. Let $E_1(R,T)$ = exponent of $Pr{\mathcal{E}_1}$. The other exponent

 $E_2(R,T) = \begin{cases} \text{decoding error exp} & \text{erasure mode} \\ \text{expected list size exp} & \text{list mode} \end{cases} = E_1(R,T) + T.$

Example 2: Erasure/List S–W Decoding (Cont'd)

Model: A double–BSS with a BSC(p) in between.

 $E_1^{\mathsf{tce}}(R,T) \ge E_1^{\mathsf{Forney}}(R,T)$ always.

For some regions in the plane R—T, $E_1^{tce}(R,T)$ may be larger than

 $E_1^{\text{Forney}}(R,T)$ by an arbitrarily large factor!

1. For R > h(p) and $T < \ln \frac{p}{1-p}$:

$$E_1^{\text{Forney}}(R,T) \le R + |T| < \infty; \quad E_1^{\text{tce}}(R,T) = \infty.$$

2. Consider the case of very weakly correlated sources, i.e., $p = \frac{1}{2} - \epsilon$, $|\epsilon| \ll 1$. For $R \in [h(p), \ln 2]$ and $T = -\tau \epsilon^2$ with $\tau > 4$:

$$E_1^{\text{Forney}}(R,T) \le (\tau+2)\epsilon^2, \quad E_1^{\text{tce}}(R,T) \ge \left[\frac{\tau(\tau+8)}{16} - 1\right]\epsilon^2.$$

Example 3: Typical Random Codes (2017)

While traditional random coding error exponents are defined as

$$E_{\mathbf{f}}(R) = \lim_{n \to \infty} \left[-\frac{\ln \mathbf{E} P_{\mathbf{e}}(\mathcal{C}_n)}{n} \right],$$

typical-code error exponents are defined as

$$E_{\mathsf{typ}}(R) = \lim_{n \to \infty} \left[-\frac{\mathbf{Eln}P_{\mathbf{e}}(\mathcal{C}_n)}{n} \right].$$

9 By Jensen's inequality,
$$E_{typ}(R) \ge E_r(R)$$
.

• $E_{r}(R)$ – dominated by bad codes; $E_{typ}(R)$ dominated by typical codes.

Let
$$\mathcal{G}_E = \{ \mathcal{C} : P_{\mathbf{e}}(\mathcal{C}) \stackrel{\cdot}{=} e^{-nE} \}.$$

$$\overline{P_{\mathbf{e}}(\mathcal{C})} \stackrel{\cdot}{=} \sum_{E} P(\mathcal{G}_{E}) \cdot e^{-nE} \stackrel{\cdot}{=} P(\mathcal{G}_{E}^{*}) \cdot e^{-nE^{*}},$$

whereas $E_{\text{typ}}(R) = E_0$, where $P[\mathcal{G}_{E_0}] \to 1$.

Example 3: Typical Random Codes (Cont'd)

We derive the exact typical-code error exponent for a class of stochastic decoders,

$$P(\hat{m} = m | \boldsymbol{y}) \propto \exp\{ng(\hat{P}_{\boldsymbol{x}_m} \boldsymbol{y})\}.$$

and show that

$$E_{\mathsf{typ}}(R) = E_{\mathsf{ex}}(2R) + R,$$

Extending Barg & Forney (2002) in several directions:

- General DMC is considered, not merely the BSC.
- Covering a wider family of decoders.
- Ensemble of constant composition codes optimal PI distribution.
- \blacksquare Relation to expurgated exponent for all R and a general decoder.
- The analysis technique is applicable also to more general scenarios.

Example 3: Typical Random Codes (Cont'd)

Particularizing to ML decoding, the error exponent formula includes minimization subject to the constraint,

 $\mathbf{E}_Q \ln W(Y|X') \ge \max\{\mathbf{E}_Q \ln W(Y|X), \mathbf{D}(R, Q_Y)\},\$

 $D(R, Q_Y) = \sup\{\mathbf{E}_Q \ln W(Y|X''): \ \mathbf{I}_Q(X''; Y) \le \mathbf{R}, \ (Q_Y \times Q_{X''|Y})_X = Q_X\},\$

being the typical highest score of an incorrect message.

A technical issue: handling summations of exponentially many fractions with random denominators – exploit concentration properties.

$$\mathbf{E}\left[\frac{1}{M}\sum_{m}\sum_{m'\neq m}\sum_{\boldsymbol{y}}P(\boldsymbol{y}|\boldsymbol{X}_{m})\cdot\frac{P(\boldsymbol{y}|\boldsymbol{X}_{m'})}{P(\boldsymbol{y}|\boldsymbol{X}_{m})+\sum_{\tilde{m}\neq m}P(\boldsymbol{y}|\boldsymbol{X}_{\tilde{m}})}\right]^{\rho}$$

Example 4: Broadcast Channels (R. Averbuch)

- Exact exponents for the weak and strong user with optimal decoders.
- Universal decoders for both users, achieving the same error exponents.
- Significant improvement and simplification of earlier results.
- Gallager-style lower bounds for both users.
- Expurgated exponents (joint work also with N. Weinberger).

Example 5: Channel Decoding with VQ'ed Codewords



- Rate- R_c "codebook" of y's, quantized versions of corresponding x's.
- Motivation: biometric identification (enrollment vs. authentication).
- Objectives: ensemble performance; universal decoding.
- Dasarthy & Draper (2011): MMI decoder. Can we improve? Yes!
- **Difficulty:** the effective channel, $\{P(\boldsymbol{z}|\boldsymbol{y})\}$, is complicated:

$$P(\boldsymbol{z}|\boldsymbol{y}_m) = \frac{P(\boldsymbol{y}_m, \boldsymbol{z})}{P(\boldsymbol{y}_m)} = \frac{\sum_{\boldsymbol{x}} G(\boldsymbol{x}) W(\boldsymbol{z}|\boldsymbol{x}) \mathcal{I}\{f(\boldsymbol{x}) = \boldsymbol{y}_m\}}{\sum_{\boldsymbol{x}} G(\boldsymbol{x}) \mathcal{I}\{f(\boldsymbol{x}) = \boldsymbol{y}_m\}}$$

Example 5: Decoding with VQ'ed Codewords (Cont'd)

Main contributions:

- Exponentially tight bound on the ensemble performance.
- Improvement relative to Dasarathy & Draper (2011).
- Universal decoder a.g.a. ML decoder ($\forall x, z : W(z|x) > 0$).
- Also a.g.a. any decoder that depends on joint empirical statistics ($\forall W$).
- A good approximation to the channel $\{P(\boldsymbol{z}|\boldsymbol{y})\}$.

Example 5: Decoding with VQ'ed Codewords (Cont'd)

Ensemble of VQ's:

- \forall input type, Q_X , choose $Q_{Y|X}$ (s.t. compression constraints).
- Solution Representation Representation $\mathcal{T}(Q_Y)$, with $R_Q = I_Q(X;Y) + \Delta$.
- Randomly rank all members of every $\mathcal{T}(Q_{Y|X}|x)$.

• Let
$$M(\boldsymbol{x}, \boldsymbol{y}) = \text{rank of } \boldsymbol{y} \in \mathcal{T}(Q_{Y|X}|\boldsymbol{x}).$$

- Code ensemble: random codebook + random rank function.
- Quantize x to $y \in \mathcal{T}(Q_{Y|X}|x) \cap \text{code}$ with the smallest M(x, y).

Example 5: Decoding with VQ'ed Codewords (Cont'd)

For most codes in the ensemble, we can approximate

$$P(\boldsymbol{y}_m) = \sum_{\boldsymbol{x}} G(\boldsymbol{x}) \cdot \mathcal{I}\{f(\boldsymbol{x}) = \boldsymbol{y}_m\} \stackrel{\cdot}{=} \exp\{-n\alpha(\hat{P}\boldsymbol{y}_m)\},\$$

where $\alpha(\cdot)$ has a certain single–letter formula.

The proposed modified MMI decoder is of the form

$$\hat{m} = \operatorname{argmin}_{m} \left\{ \log N(\boldsymbol{y}_{m} | \boldsymbol{z}) - n\alpha(\hat{P} \boldsymbol{y}_{m}) \right\},\$$

where

$$N(\boldsymbol{y}_m | \boldsymbol{z}) = \left| \mathcal{T}(\boldsymbol{y}_m | \boldsymbol{z}) \cap \mathcal{C} \right|,$$

 \mathcal{C} being the VQ code.

Some Other Works

- Improved bounds for erasure/list decoding (2008).
- The interference channel (w. Etkin & Ordentlich, 2010).
- The broadcast channel (w. Kaspi, 2011).
- Exact bounds for erasure/list decoding (w. Somekh–Baruch, 2011).
- Expurgation (w. Scarlett, Peng, Guillén i. Fabregas, Martinéz, 2014).
- Erasure/list for S–W decoding (2014).
- Codeword or noise? (w. Weinberger, 2014).
- Optimal bin index decoding (2014).
- Correct wiretapper decoding (2014).
- Statistical physics of random binning (2015).
- Universal source/channel with SI (2016).
- Simplified erasure/list decoding (w. Weinberger, 2017).
- Improved exponents for the IFC (w. Huleihel, 2017).

Some Other Works (Cont'd)

- Joint channel detection & coding (w. Weinberger, 2017).
- Generalized likelihood decoder (2017).
- Exact secrecy exponents (w. Bastani-Parizi & Telatar, 2017).
- Universal decoding for VQ'ed codewords (2017).
- Exact exponents & universal decoding for the ABC (w. Averbuch, 2017).
- Ensemble performance of biometric ident. systems (2017).
- Mismatched ISI channels (w. Huleihel, Salamatian & Médard, 2017).
- V–L codes with single–bit feedback (w. Ginzach & Sason, 2017).
- Typical–code random coding exponents (2017).
- Expurgated bounds for the ABC (w. Averbuch & Weinberger, 2017).
- 2nd order & moderate deviations in error+erasure (Hayashi & Tan, 2015).
- Residual uncertainties under Rényi entropies (Hayashi & Tan, 2016).
- Mismatched decoding (Scarlett, Ph.D. thesis, 2014).

Future Challenges and Open Problems

- Handling ensembles of linear/lattice/convolutional/LDPC codes, etc.
- Further results on typical random codes (multi-user configurations).
- Simplify optimization problems (e.g., Gallager-style bounds).
- A more solid theory for the extended MoT (for exponential families).

Thank U 4 Coming & Listening!